

~~b.~~  
~~52~~  
4. The method of claim 1 wherein step (c) further comprises obtaining the control voltage by integrating a voltage across a current sensing resistor.

~~53.~~  
5. The method of claim 1 wherein step (a) further comprises the steps of:  
(a)(i) enabling the calibrating of the predetermined voltage threshold.

~~53.~~  
6. (Amended) The method of claim 5, wherein step (a)(i) further comprises the steps of:  
(a)(ii) applying a signal from a digital-to-analog converter (DAC) to the input of a comparator;  
(a)(iii) applying a finite specific reference signal to simulate the monitoring of one of the current and voltage applied to the spindle motor; and  
(a)(iv) adjusting the signal from the DAC to compensate for offsets of the circuitry.

~~53.~~  
7. (Amended) The method of claim 1 further comprising the step of:  
(e) waiting a fixed period of time;  
(f) reapplying power to the motor; and  
(g) repeating steps (b) - (g).

8. (Amended) A method for controlling the current drawn from a power supply in a computer system by a spindle motor, comprising the step of decoupling the power supply from the spindle motor if a control voltage exceeds a predetermined voltage threshold.

~~53.~~  
13. (Amended) A data storage device, comprising:  
at least one spindle motor;  
a power supply electrically coupled to the spindle motor; and  
a spindle motor controller, wherein the spindle motor controller measures and, if a threshold value is at least met, decouples power to the spindle motor.

~~14.~~ The data storage device of claim 13 wherein the spindle motor controller further comprises:

a driver control function programmed into the motor controller which disables a spindle motor driver for a fixed period of time.

~~15.~~ (Amended) The data storage device of claim 13 wherein the spindle motor controller decouples power when a control voltage, proportional to at least one of a motor current and motor voltage, is at least equal to a threshold voltage.

~~16.~~ The data storage device of claim 14 wherein the driver control function is enabled when a signal proportional to a current applied to the spindle motor exceeds a predetermined threshold.

~~17.~~ (Amended) The data storage device of claim 16 wherein the power supply is coupled to the spindle motor for at least one of a start-up sequence and a run sequence.